

by  $G$  and its determinant by  $|G|$ . We assume that the degenerate system ( $\epsilon = 0$ ) has a solution which can be continued up to  $t = \tau$  where  $\tau$  is such that for the solution in question  $|G(x(\tau), u(\tau), \tau, 0)| = 0$ . Part of our sufficient condition for the perturbed system to have a solution is the requirement that the characteristic equation

$$|g_{ij}(x(\tau), u(\tau), \tau, 0) - \lambda \delta_{ij}| = 0$$

have  $\lambda = 0$  as a simple root.

<sup>1</sup> M. Nagumo, Über das Verhalten der Integrals von  $\lambda y'' + f(x, y, y', \lambda) = 0$  für  $\lambda \rightarrow 0$ . *Proc. Phys. Math. Soc. Japan*, **21**, 529–534 (1939). I. M. Volk, A Generalization of the Method of Small Parameter in the Theory of Non-Linear Oscillations of Non-Autonomous Systems. *C. R. (Doklady) Acad. Sci. U.S.S.R.*, **51**, 437–440 (1946). Volk considers (1) where the  $X_i$  are meromorphic functions of  $\epsilon$  for small  $\epsilon$  and periodic in  $t$ . K. O. Friedrichs and W. R. Wasow, Singular Perturbations of Non-Linear Oscillations. *Duke Math. Jour.*, **13**, 367–381 (1946). Here the  $X_i$  are not functions of  $t$  and for  $i \leq n-1$  are not functions of  $\epsilon$ .  $X_n$  contains  $\epsilon$  in the form of a factor  $1/\epsilon$ .

<sup>2</sup> D. A. Flanders and J. J. Stoker, *The Limit Case of Relaxation Oscillations, Studies in the Linear Vibration Theory*, New York Univ., 1946.

<sup>3</sup> This is the system, except that  $t$  is not necessarily excluded from the right members, which is considered by Friedrichs and Wasow, *loc. cit.*

<sup>4</sup> See Friedrichs and Wasow, and Volk, *loc. cit.*, for continuous cases where right members do not and do, respectively, depend on  $t$ .

## A MINIMUM PROBLEM ABOUT THE MOTION OF A SOLID THROUGH A FLUID

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1. An incompressible frictionless fluid of uniform density  $\rho$  fills the whole space outside a moving solid and is at rest at infinite distance. The motion of the solid is one of pure translation. The magnitude of the velocity is  $U$ , its direction cosines with respect to a coördinate system fixed in the solid  $\lambda, \mu, \nu$ . The kinetic energy of the fluid is of the form

$$T = \frac{1}{2}MU^2.$$

The quantity  $M$ , called the virtual mass, depends on the direction of the velocity:

$$M/\rho = A\lambda^2 + B\mu^2 + C\nu^2 + 2A'\mu\nu + 2B'\nu\lambda + 2C'\lambda\mu.$$

$A, B, C, A', B', C'$  are uniquely determined if the shape and size of the solid and the relative location of the coördinate system and the solid are given.

A closer study of the dependence of  $A$ ,  $B$ ,  $C$ ,  $A'$ ,  $B'$  and  $C'$  on geometric data may seem desirable.<sup>1</sup> Taking a first step in such a study, we consider the *average virtual mass*  $\bar{M}$ , obtained by averaging  $M$  over all directions  $\lambda$ ,  $\mu$ ,  $\nu$  and assuming  $\rho = 1$ :

$$\bar{M} = (A + B + C)/3.$$

$\bar{M}$  is independent of the location of the coördinate system and depends only on the size and shape of the solid. It is easy to show that *of all ellipsoids with given volume the sphere has the minimum average virtual mass*. It would be natural to suspect that this statement remains true if for "ellipsoids" we substitute "solids." At any rate, I shall prove the analogous general theorem in two dimensions.

2. We consider now the two-dimensional motion of an incompressible frictionless fluid of uniform density  $\rho$  that fills the space around a cylinder of infinite length. The motion is parallel to a plane, the plane of the complex variable  $z$ , that is perpendicular to the cylinder and intersects it in a closed curve  $C$  (the notation of section 1 has been dropped). The exterior of  $C$  is mapped conformally onto the exterior of the unit circle in the  $\zeta$ -plane so that the points at infinity correspond. Thus,  $z$  moving outside  $C$  is represented by the series

$$z = \lambda \left( \zeta + c_0 + \frac{c_1}{\zeta} + \frac{c_2}{\zeta^2} + \dots \right) \quad (1)$$

convergent for  $|\zeta| > 1$ . The number  $\lambda$  is positive.

We begin with the case in which the motion of the fluid at infinite distance is parallel to the real axis and has the velocity  $U$  (uniform flow disturbed by a fixed cylindrical obstacle). The corresponding motion in the  $\zeta$ -plane, around a circular cylinder and with velocity  $U\lambda$  at infinity, has the complex potential

$$\chi' = U\lambda \left( \zeta + \frac{1}{\zeta} \right). \quad (2)$$

Yet (2) represents also the complex potential for the  $z$ -plane provided that  $z$  and  $\zeta$  are linked by the mapping (1) that transforms streamlines into streamlines and, especially, the unit circle of the  $\zeta$ -plane into  $C$ .

3. To the motion just considered we add a uniform velocity  $U$  directed along the *negative* real axis. We obtain thus a new motion (disturbance of a fluid which is at rest at infinite distance by a cylinder moving through it sidewise to the left). The complex potential of this motion is obviously

$$\chi = \chi' - Uz = U \left[ \lambda \left( \zeta + \frac{1}{\zeta} \right) - z \right] \quad (3)$$

where  $z$  and  $\zeta$  remain linked by (1). (Of course the coördinate system re-

mains fixed with respect to the solid.) The velocity at the point  $z$  is  $\bar{w}$ , conjugate to

$$w = \frac{d\chi}{dz} = U \left[ \lambda \left( 1 - \frac{1}{\zeta^2} \right) \frac{d\zeta}{dz} - 1 \right]. \quad (4)$$

The kinetic energy of a layer of the fluid, of unit thickness and parallel to the  $z = x + iy$  plane, is

$$\frac{1}{2} \rho \iint |w|^2 dx dy = \frac{1}{2} M U^2. \quad (5)$$

The integral is extended over the exterior of  $C$ , and  $M$  is the *virtual mass per unit height*. From (4) and (5) we obtain

$$\begin{aligned} M/\rho &= \iint \left| \lambda \left( 1 - \frac{1}{\zeta^2} \right) \frac{d\zeta}{dz} - 1 \right|^2 dx dy \\ &= \iint \left| \frac{dz}{d\zeta} - \lambda \left( 1 - \frac{1}{\zeta^2} \right) \right|^2 d\xi d\eta; \end{aligned} \quad (6)$$

the latter integral is extended over the exterior of the unit circle in the  $\zeta = \xi + i\eta$  plane. Introducing (1) and polar coordinates, we obtain from (6) in the usual way that

$$M/\rho = \pi \lambda^2 (|c_1 - 1|^2 + 2|c_2|^2 + 3|c_3|^2 + \dots). \quad (7)$$

Now the area of  $C$  or, what is numerically the same, the volume  $V$  of the moving cylinder per unit height is

$$V = \pi \lambda^2 (1 - |c_1|^2 - 2|c_2|^2 - 3|c_3|^2 - \dots). \quad (8)$$

This is well known and obtained by a computation analogous to the one just sketched. It follows from (7) and (8) that

$$V + M/\rho = 2\pi \lambda^2 (1 - \Re c_1). \quad (9)$$

where  $\Re c_1$  denotes the real part of  $c_1$ .

4. Now, we wish to obtain  $M_\alpha$ , the virtual mass per unit height corresponding to a direction of the velocity that includes the angle  $\alpha$  with the direction just considered. We reduce this problem to the foregoing by a rotation, introducing the new complex variables  $z'$  and  $\zeta'$ ,

$$z' = e^{i\alpha} z, \quad \zeta' = e^{i\alpha} \zeta.$$

We obtain from (1) that

$$z' = \lambda \left( \zeta' + c_0 e^{i\alpha} + \frac{c_1 e^{2i\alpha}}{\zeta'} + \frac{c_2 e^{3i\alpha}}{\zeta'^2} + \dots \right) \quad (1')$$

Substituting  $c_1 e^{2i\alpha}$  for  $c_1$  in (9), we obtain

$$V + M_\alpha/\rho = 2\pi\lambda^2(1 - \Re c_1 e^{2i\alpha}) \quad (9')$$

and hence

$$V + M_{\alpha+\pi/2}/\rho = 2\pi\lambda^2(1 + \Re c_1 e^{2i\alpha}) \quad (10)$$

We define  $\bar{M}$ , the average virtual mass per unit height by

$$\bar{M} = (1/2\pi\rho) \int_0^{2\pi} M_\alpha d\alpha = (1/2\rho)(M_\alpha + M_{\alpha+\pi/2}). \quad (11)$$

( $\bar{M}$  has, in fact, the dimension of an area, and so has  $V$ .) From (9'), (10) and (11) we find finally

$$V + \bar{M} = 2\pi\lambda^2 \quad (12)$$

5. Now  $\lambda$  is the so-called outer radius of  $C$  (that is the radius of the circle onto the exterior of which the exterior of  $C$  is so mapped that the points at infinity correspond to each other with unit magnification). It follows from (8) (and is well known) that

$$V < \pi\lambda^2.$$

unless  $C$  is a circle. Therefore, by (12),

$$\bar{M} > V$$

with the same proviso. For the circle, however,  $\bar{M} = V$ . Thus, we have proved that of all cylinders having the same area of the cross-section, the circular cylinder has the minimum average virtual mass per unit height.

We can derive another result from (12): the average virtual mass per unit height decreases by symmetrization. Indeed, we know that symmetrization leaves  $V$  unchanged and decreases the outer radius  $\lambda$ .<sup>2</sup>

<sup>1</sup> This is suggested by a systematic study of the dependence of the capacity on geometric data which has been undertaken recently by Mr. G. Szegő and the author.

<sup>2</sup> See G. Pólya and G. Szegő, "Inequalities for the Capacity of a Condenser," *Amer. Jour. Math.*, 67, 1-32 (1945), especially pp. 13-14.